



Training Modules for Mobile 3D Sensor



Connect



Learn



Solve



Mobilise



A core part of our philosophy at ifm is that we work closely with our customers. We want to understand each customer's business and create solutions that work best for them. We also want our customers to grow. Which is why we are offering a new range of training seminars for our mobile solutions range. As with our solutions, we will customise every training session according to an individual customer's needs and requests. Please see the inside of this booklet for more details of the training modules we have available.

Training Modules



MOBILE 3D SENSOR

CODE	MODULE	DURATION	CODE	MODULE	DURATION
OMGT01	Basic Training O3M (customer application focused) Introduction to ifm vision System <ul style="list-style-type: none"> • Motivation • Application discussion Hardware components <ul style="list-style-type: none"> • Sensors, illumination unit, cables • Wiring concept • Mounting accessories Software configuration <ul style="list-style-type: none"> • Calibration • Filters Setup • Inclusion & Exclusion Zones setup • Region of Interests setup • Video feed overlays Firmware <ul style="list-style-type: none"> • Distance image • Object detection • Line guidance Additional device functions <ul style="list-style-type: none"> • Creating application specific FCR • Standby / Wake Up commands Communication & Data Interpretation <ul style="list-style-type: none"> • CAN & Ethernet IP data mapping • CodeSys libraries for data interpretation • Programming logic (Ethernet & CAN PLC) • Practical exercise (customer application focused) 	1 Day		<ul style="list-style-type: none"> • Distance of separation between modules • Obstruction distance requirement Software Installation <ul style="list-style-type: none"> • Download procedure & Installation Software Operation <ul style="list-style-type: none"> • Navigation • Status • Monitoring window • Device application setup • Bus settings • Coordinate system calibration • Live image display Filters <ul style="list-style-type: none"> • Live image display • Signal quality • Noise reduction • Reflector threshold value • Unwanted particle detection Distance Image <ul style="list-style-type: none"> • Application • Selection of result • Region of interest • Output value setup Distance Object <ul style="list-style-type: none"> • Application • Detection – Standard & Reflector • Collision avoidance application variant Line Guidance <ul style="list-style-type: none"> • Navigation • Area search • Edge detection • Filters Programming <ul style="list-style-type: none"> • KVASER CAN and EthernetIP data interpretation • CodeSys programming • Practical Exercises (Ethernet/CAN PLC) 	
<i>Basic PLC Programming and basic knowledge of CAN bus</i>					
OMGT02	Advanced Training O3M (core software and hardware training) Introduction to vision theory <ul style="list-style-type: none"> • Time Of Flight theory • Coordinate system Hardware Installation <ul style="list-style-type: none"> • Sensor, Illumination unit and cables connection • Programming cable and adapter • Mounting accessories 	1.5 Days		PLC Programming and basic knowledge of CAN bus	



Meet the experts

Interested in training?

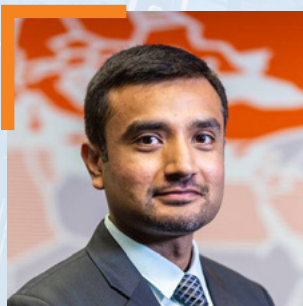
We'd love to discuss training options with you! We will customise a training session or series of training sessions to suit your needs.

Phone us on 1300 365 088



Aditya Kunder

Mobile Industry
Sales Manager



Syed Ahmad

Senior Field Technical
Support Engineer

Click or Scan for
more information



sales.au@ifm.com
www.ifm.com/au